

MUSIC STRUCTURE DISCOVERY: MEASURING THE "STATE-NESS" OF TIMES

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1. STATE AND SEQUENCE APPROACH

Music Structure Discovery (MSD) aims at estimating the underlying structure of a music track using observations of the audio signal. For this, a given time t_i of a music track is supposed to belong to one of the following categories:

- if t_i contains information similar to its adjacent times, t_i is said **homogeneous** [7] and belongs to a "state" [8],
- if t_i is similar to a foreign time t_j , and if the same is true for t_{i+l} $l \in [1, \lambda]$ (similar to t_{j+l}), we say that the corresponding segments are **repetitions** [7]. - If the corresponding times t_{i+l} are similar to their adjacent times than we have a "state repetition". - If this is not the case, we say that the times t_{i+l} and t_{j+l} belong to a "sequence" [8] of length λ which is **instantiated** at time t_i and at time t_j .
- if t_i is not similar to any other times, t_i is a **null-time**.

This subdivision has lead to two types of approaches to estimate the music structure: • the state approach, which is used to detect states (being repeated or not) and • the sequence approach, which is used to detect sequences (i.e. repetitions which are not states). See [8] for more details. This subdivision is summarized in the table below.

	Homogeneous	Non-Homog.
Repeated	State approach	Sequence approach
Non-Rep.	State approach	Null

Much more MSD systems have been proposed for the state approach. This is probably due to the fact that this approach can rely on well-established algorithms for segmentation (novelty measure of [1]), clustering [10] or hidden Markov models. In the state approach, there is no need to distinguish between repeated and non-repeated times since both will end up in states. The state approach is however not able to deal with non-homogeneous repeated times. This is the goal of the sequence approach.

The sequence approach first necessitates to distinguish the repeated times from the null times since only the repeti-

tions will be used for the structure. Hence, the majority of the sequence approaches proceed in three successive separated stages: (1) extraction of audio observations, (2) detection of repetitions (sequence-instantiations) (3) connection of the detected sequence-instantiations to each others in order to estimate the sequences hence the structure.

1.1 Choice between state and sequence approach

To estimate the structure of a track, the choice between a state and a sequence approach depends on (A) the property of the music composition/production itself and (B) the audio observation we have from it. This second point can be subdivided into (B.1) the signal observations being used (B.2) the observation window length. Given a track and its observations, an automatic way to estimate the most appropriate approach to be used (among the state and sequence) would be beneficial. We propose here a measure which allows assigning each time of a track to one of the two approaches.

2. MEASURING THE STATE-NESS OF A TIME

As previously said in a MSD system, a given time t_i belongs to one of the following classes: - homogeneous/ (repeated or not), - sequence (which are by definition repeated), - null. Corresponding to these classes are specific observations in the Self Similarity/Distance Matrix (SSM):

- homogenous/state: the local area around t_i in the main diagonal has continuous large values,
- sequence: the time corridor including t_i enclose at least one diagonal stripe,
- nul: neither the state or sequence conditions are observed.

Using this, we propose the "state-ness" coefficient $c(\tau)$ which represent the possibility to represent a time τ by a "state". For this, we first define the sub-matrix along the main diagonal of length L

$$\underline{E}_\tau(t_i, t_j) = \underline{E}(t_i \in [\tau, \tau + L], t_j \in [\tau, \tau + L]) \quad (1)$$

where $\underline{E}(t_i, t_j)$ is the SSM provided by a specific MSD system and L is a fixed parameter set to 5s. We then compute the ratio of the mean value of the block \underline{E}_τ over the mean value of its diagonal. If the block represents a "state" then

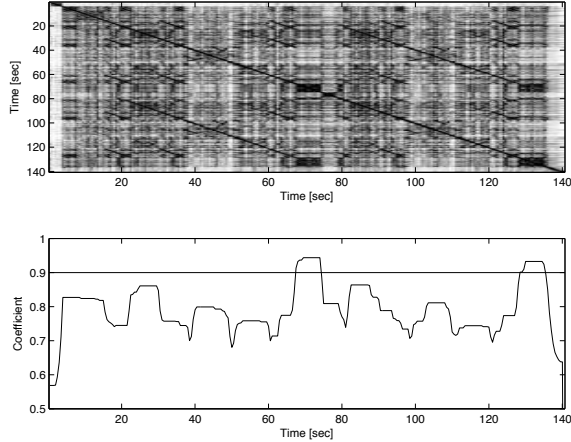


Figure 1. [Upper part]: Self Similarity Matrix [Lower Part]: $c(\tau)$ for $L = 5s$ and a threshold at 0.9. On track: "If I Needed Someone" from The Beatles "Rubber Soul" album.

the mean value of the block will be close to the mean value along its diagonal. We also add a constraint related to the homogeneity of the block by subtracting to the mean value its standard deviation:

$$c(\tau) = \left(\mu(\underline{E}_\tau) - \sigma(\underline{E}_\tau) \right) / \left(\mu(\text{diag}(\underline{E}_\tau)) \right) \quad (2)$$

where μ denotes the mean value and σ the standard deviation. By experiments, we found that times for which $c(\tau) \geq 0.9$ correspond to "states". We illustrate this in Figure 1 where the values of $c(\tau)$ indicate two "states" around times 70s and 130s. The remaining times of this track either belong to sequence-instantiations or are null-times.

3. EXEMPLIFYING

We illustrate here the use of the "state-ness" coefficient $c(\tau)$. For the computation of the SSM we use the system proposed in [9]: 13 MFCCs (excluding the 0th coefficient) combined with 12 Spectral Contrast Measures and Spectral Valley Measures [5] and 12 Pitch-Class-Profile coefficients [2]. Each dimension of the features is then modeled over time (texture window) by its mean value over a sliding window of length $P = 1s$ (or $P = 4s$) with a 500ms hop size. We refer the reader to [9] for more details on the exact computation of the Self Similarity Matrix from these features. We demonstrate here the influence of the choice of P (using either short-term modeling $P = 1s$, or long-term modeling $P = 4s$) on $c(\tau)$ hence on the choice between a state of sequence approach. For each track of each test-set, we compute $c(\tau)$ for each frame of the track.

Using $P = 1s$, 6.2% of the frames of the Beatles test-set [6] have a value $c(\tau) > 0.9$. Hence, the "sequence" representation is well-suited for 93.8% of the frames. Figure 2 illustrates the evolution of $c(\tau)$ over tracks (tracks are

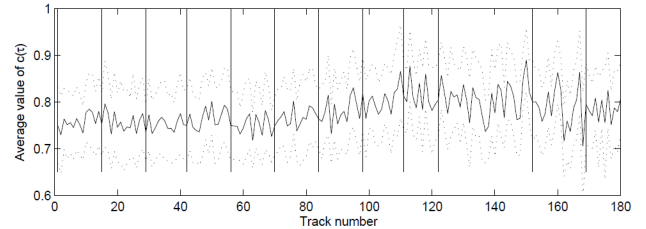


Figure 2. Average value of $c(\tau)$ over track number (dotted lines represent $\mu + \sigma$ and $\mu - \sigma$, vertical lines represent album separation) for the 180 tracks of the Beatles test-set.

arranged in recording date by album). It is interesting to note that the average-per-track $c(\tau)$ tends to increase over the years, which could be interpreted as a more important use of "states" in the music structure process of The Beatles over times. The same applied to the RWC-Popular-Music test-set [4] [3] leads to 3.98% of the frames with $c(\tau) > 0.9$, hence belonging to states. Using $P = 4s$, the results change drastically: the state representation is now dominant among frames: 58.82% for the Beatles and 58.16% for the RWC test-set.

4. ACKNOWLEDGMENTS

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